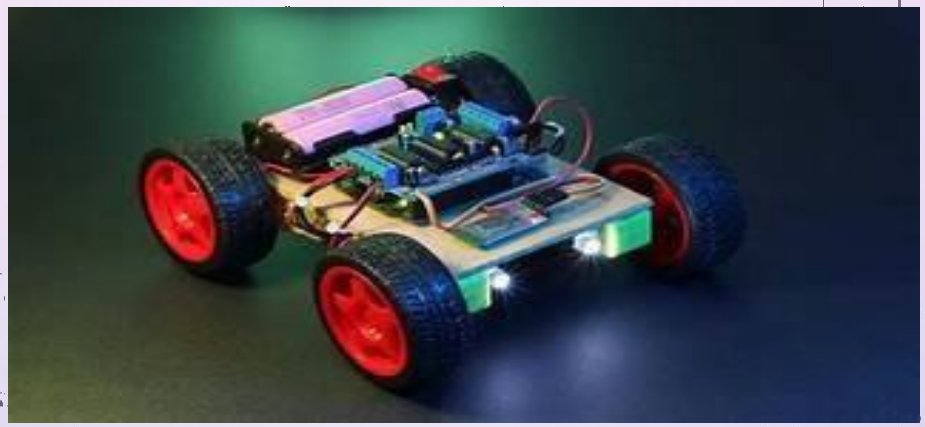
Bluetooth Controlled Car with Arduino



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List of contents:-

INTRODUCTION

- The Bluetooth control car receives commands from a Bluetooth-enabled device(Smartphone, remote control, etc) and these commands are processed by the Arduino.

- The Arduino then generates motor control signals, which are sent to the motor driver to the driver the DC motors.

- Then Finally, The motorized wheels move the car accordingly.

TOOLS

CHASSIS

- The main body of the car consists of the chassis.

- Alongside there will be four motors for the four Wheels which will lead down the car.

ARDUINO UNO R3

- The Arduino Uno is an open-source microcontroller based on the microchip ATMEGA238P microcontroller and developed by Arduino. CC.

- The board is equipped with sets of digital and analog input/output pins that may be interfaced with various expansion boards and other circuits.

L293D Motor Driver

- The Motor Driver is a module for motors that allows you a control the working speed and direction of four motors simultaneously.

- The main motor driver is designed and developed based on L293D is a 16 pins Motor Driver IC.

- This is designed to provide bio directional drive currents a voltage from 5 V to 36 V .

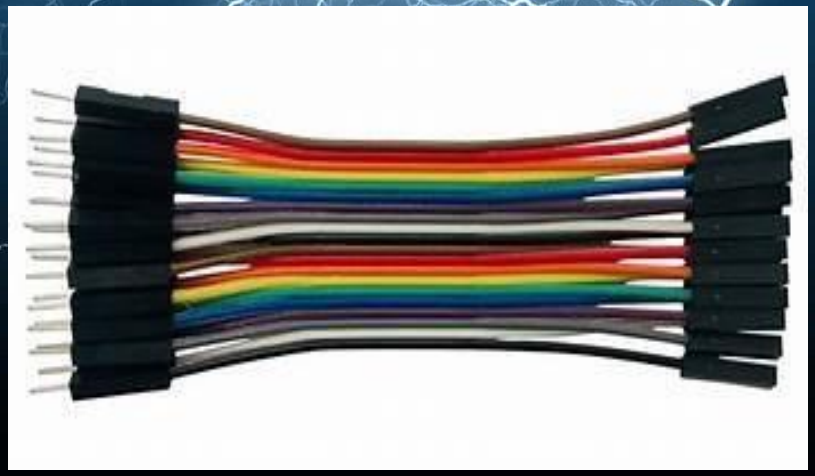
- Rotation of the motor depends on the enabled plans .

JUMPER WIRE

✓ A jump wire (Also known as jumper, jumper wire, Dupont wire) is a electrical wire or group of them in a cable, with a connector or pin at each end (or sometimes without them simply “tinned”).

✓ Which is normally used to interconnects the components of a Breadboard or other prototype or test circuit.

✓ Internally or other equipment or components without soldering.



(BATTERY)

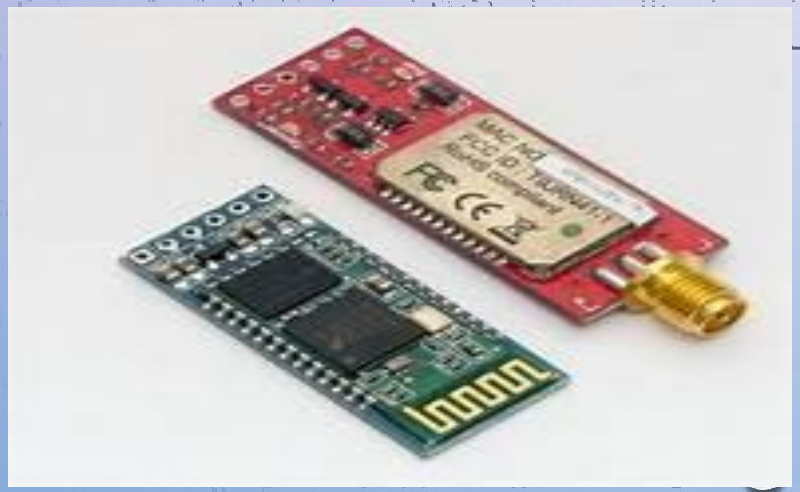
(SWITCH)

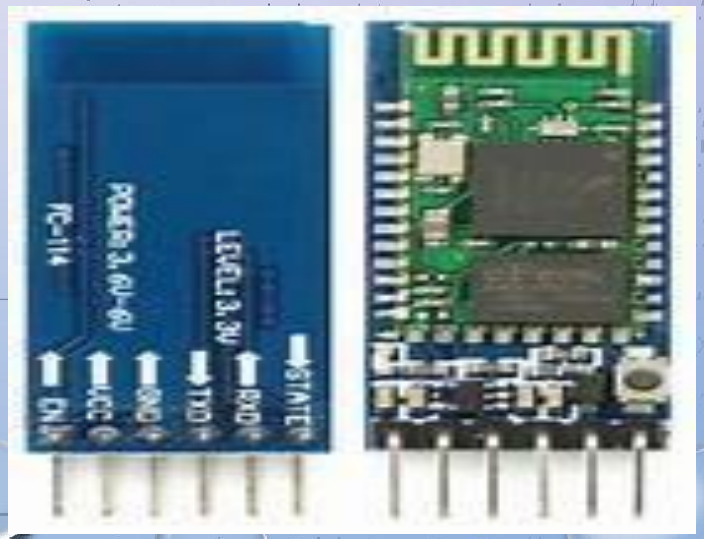
SWITCH

- A switch is used for tunneling on the power on the vehicle.
- It controls the battery connection of the vehicle.

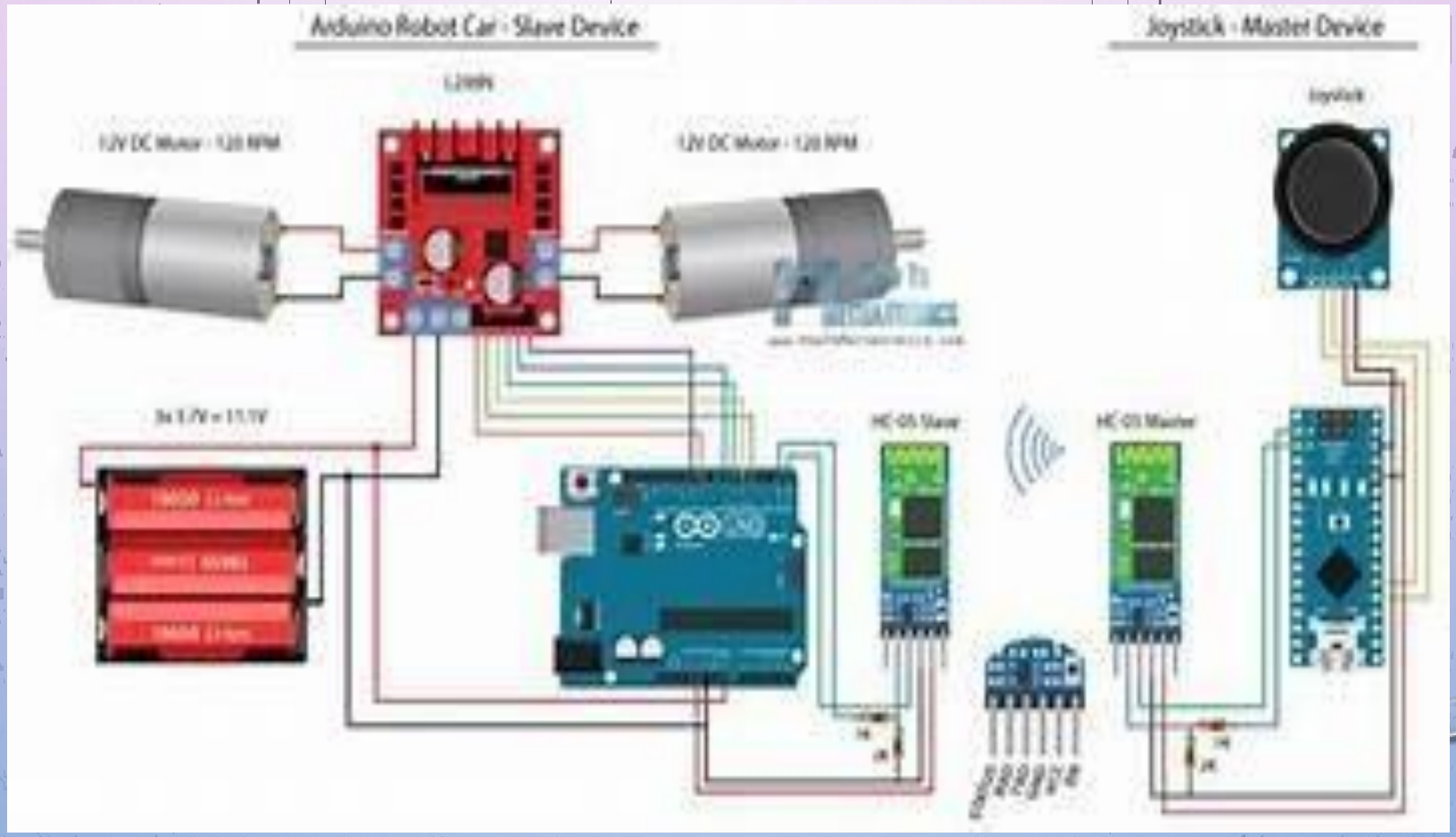
BLUETOOTH MODULE

- HC-05 6 pin wireless serial Bluetooth module is a Bluetooth module for use with any microcontroller.
- It uses the UART protocol to make it easy to send and receive data wirelessly.
- The HC-06 module is a slave-only device.
- This means that is can connect to most phones and computers using Bluetooth technology.





PIN DIAGRAM & CONNECTION



FLOW CHART OF IMPLEMENTATION

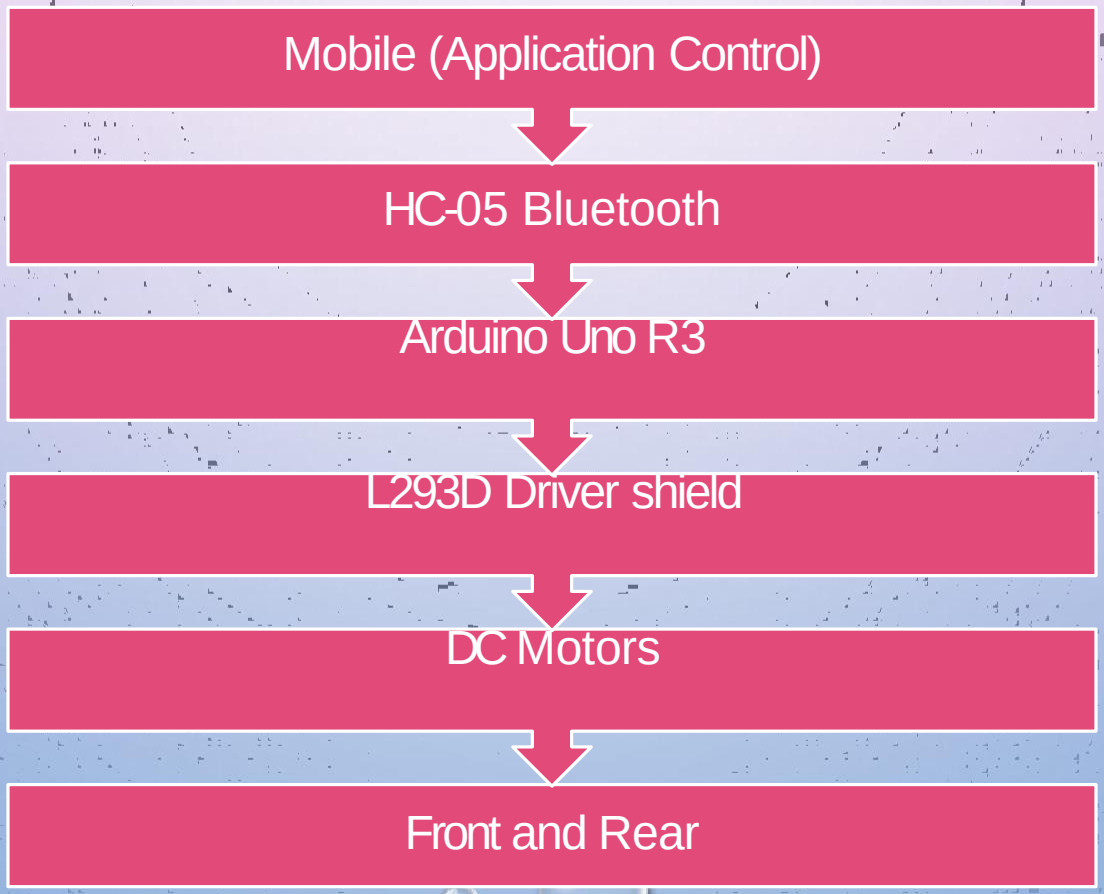
Give command using app or remote and send it through wireless of Bluetooth system .

Receive data from the app using Bluetooth module.

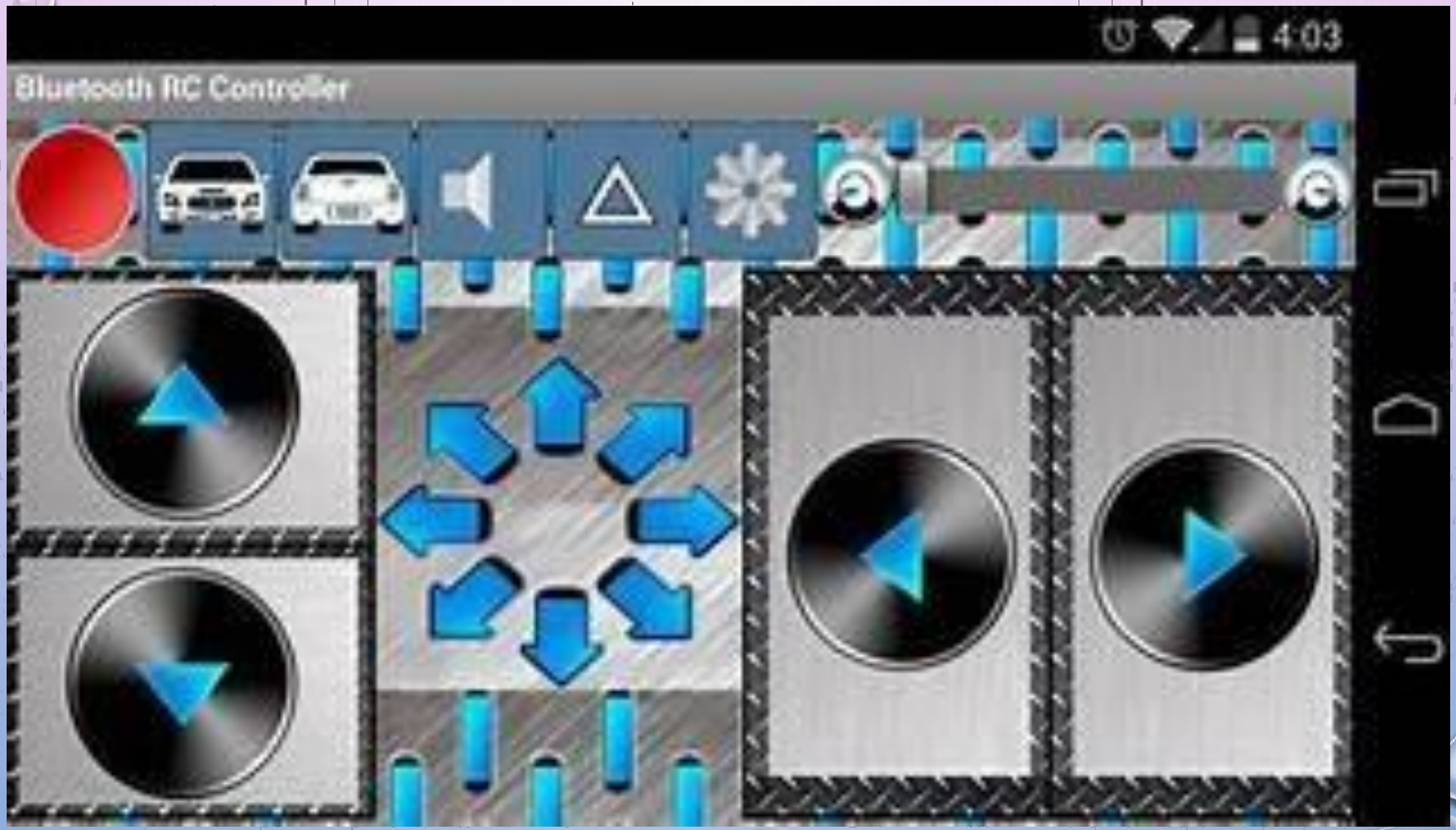
Recognize data commands by the microprocessor.

Execute the instruction by controlling the motor driver.

COMPONENTS OF BLUETOOTH CONTROL CAR



APPLICATION CONTROLLER



CONCLUSION

- **The main conclusion is that Bluetooth Module has its limited range.**
- **If we go > 100 it gets automatically disconnected.**
- **The instruction from Arduino Application are given to microcontroller via Bluetooth module.**


Thank you